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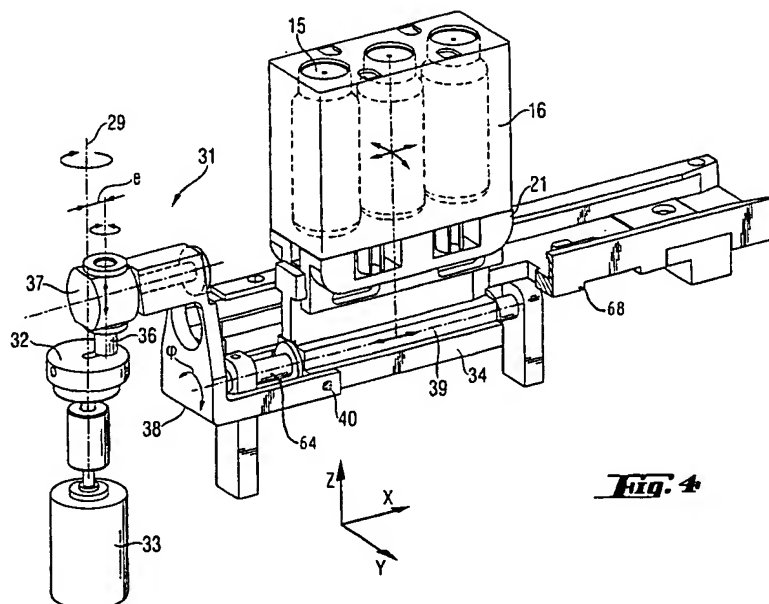
(54) **Test tube stand with a movable section for shaking the sample.**

(57) A rack (11) for holding containers containing liquids used in clinical chemistry analyzers. The rack comprises

(a) a frame (12) having two or more sections, each section (13, 14) being adapted for receiving a liquid containing component,
at least one of the sections (13) of said frame (12) being adapted for receiving a first liquid containing component which is adapted for being removably

but tightly mechanically connected to said frame,

(b) at least one movable part (21) adapted to be removably coupled to a shaker device, said movable part being adapted for receiving and holding a second liquid containing component,
at least one of the sections (14) of said frame being adapted for receiving said movable part (21) and allowing motion of said movable part (21) within predetermined limits.

**Fig. 4**

Description

[0001] The invention concerns a rack for holding containers containing liquids used in clinical chemistry analyzers.

[0002] The invention further concerns an automatic analyzer for analyzing biological samples by means of a clinical chemistry method.

[0003] In automatic clinical chemistry analyzers racks are used for holding containers of liquids required for performing analysis of samples to be analyzed. Some of those liquids are e.g. solutions containing magnetic particles which should be uniformly distributed in the solution; such liquids require agitation during predetermined time intervals, whereas other required liquids require no agitation at all.

[0004] In prior art apparatuses it has therefore been necessary to have additional racks for containers which contain liquids that require agitation and agitating means connectable to such racks or to selectively transport such containers to a station for agitating liquid containers and thereby the liquids contained therein. A disadvantage of both approaches is that they increase the complexity and the manufacturing cost of automatic clinical chemistry analyzers. It is therefore desirable to have racks and analyzers which do not have this disadvantage.

[0005] A first aim of the invention is therefore to provide a rack which makes it possible to eliminate the above mentioned disadvantage.

[0006] A second aim of the invention is to provide an analyzer which makes it possible to eliminate the above mentioned disadvantage.

[0007] According to a first aspect of the invention the above mentioned first aim is achieved with a rack having the features defined by claim 1.

[0008] According to the intended use of the rack defined by claim 1, a container containing a liquid which has to be agitated is placed on a movable part of the rack which is adapted to be shaken by means of a shaker mechanism.

[0009] According to a second aspect of the invention the above mentioned second aim is achieved with an analyzer having the features defined by claim 6.

[0010] There is also a need for an analyzer having a low cost shaker device which is suitable for agitating liquids e.g. reagents contained in reagent containers located in a rack used in automatic clinical chemistry analyzers. An example of such liquid reagents are those containing magnetic particles which should be agitated in order that the magnetic particles are homogeneously distributed in the liquid.

[0011] A third aim of the invention is therefore to provide an analyzer having a low cost shaker device which is useful for the purpose just mentioned.

[0012] According to a third aspect of the invention the above mentioned third aim is achieved with an analyzer having the features defined by claim 10.

[0013] Preferred embodiments are defined by sub-

claims attached to this specification.

[0014] The subject invention will now be described in terms of its preferred embodiments with reference to the accompanying drawings. These embodiments are set forth to aid the understanding of the invention, but are not to be construed as limiting.

[0015] Fig. 1 shows a perspective view of a rack 11 according to the invention

[0016] Fig. 2 shows an exploded view of rack 11 shown by Fig. 1, removable part 21 of rack 11 and a casing 16 containing several containers 15 which each contain a liquid to be agitated.

[0017] Fig. 3 shows a perspective view of a part of an analyzer according to the invention.

[0018] Fig. 4 shows a perspective view of a first embodiment of a shaker device 31 which is part of the analyzer shown by Fig. 3.

[0019] Fig. 5 shows a partial cross-sectional view of means for coupling movable part 21 of rack 11 with a carriage 34 of a shaker device 31 by means of a leaf spring 35.

[0020] Fig. 6 shows a partial cross-sectional view of a movable part 21 of rack 11 coupled with carriage 34 of shaker device 31 by means of leaf spring 35.

[0021] Fig. 7 shows curves representing the variation with time of the components of motion of carriage 34 in three orthogonal directions X, Y, Z and of an angular component ϕ corresponding to the oscillation of the carrier around an axis of oscillation.

[0022] Fig. 8 shows a path M of a point of casing 16 when it is moved by shaker device 31 shown by Fig. 4.

[0023] Fig. 9 shows a perspective partial view of a second embodiment of an analyzer according to the invention.

[0024] Fig. 10 shows an enlarged view of a portion of Fig. 9.

[0025] Fig. 11 shows a perspective partial view of a third embodiment of an analyzer according to the invention.

[0026] Fig. 12 shows an enlarged view of a portion of Fig. 11.

[0027] Fig. 13 shows a perspective partial view of a fourth embodiment of an analyzer according to the invention.

[0028] Fig. 14 shows an enlarged view of a portion of Fig. 13.

REFERENCE NUMERALS IN DRAWINGS

[0029]

- 11 rack
- 11a rack
- 12 frame
- 13 section of frame 12
- 14 section of frame 12
- 15 liquid container
- 16 liquid container carrier (e.g. a kit of reagents)

21 movable part of rack 11
 28 encoder
 29 axis of rotation of motor shaft 71
 31 shaker device
 32 disk driven by motor 33
 33 step motor
 34 carriage of shaker device 31
 35 leaf spring
 36 eccentric pin
 37 cylindrical joint combined with a revolute joint
 38 connection piece
 39 axis of oscillation and deviation
 40 joint
 41 pin
 42 pin
 43 pin
 51 opening of removable part 21
 52 opening of removable part 21
 53 slide bearing
 61 motor shaft
 61a eccentric pin
 61b axis of eccentric pin
 62 slide bearing
 63 carriage of shaker device
 64 guiding shaft
 65 ball and socket joint
 66 electro-optical detector
 67 shaker device
 68 support plate for the frame 12 of rack 11
 70 shaker device
 71 motor shaft
 71a eccentric pin
 71b axis of eccentric pin
 72 slide bearing
 73 motor holder
 74 guiding shaft
 75 guiding shaft
 76 machine frame
 77 guiding support member
 78 ball and socket joint
 79 movable support plate for the frame 12 of rack 11a
 80 shaker device
 81 motor shaft
 81a eccentric pin
 81b axis of eccentric pin
 82 slide bearing
 83 motor holder
 84 guiding shaft
 85 guiding shaft
 86 machine frame
 87 arm
 88 ball and socket joint
 89 movable support plate

e eccentricity
 ϕ deviation angle
 S arrow for longitudinal movement
 R arrow for rotation

DETAILED DESCRIPTION OF PREFERRED EMBODIMENTS

[0030] An automatic clinical chemistry analyzer comprises in general means for handling liquids like biological samples or reagents and means for analyzing sample-reagent-mixtures. A reagent can be e.g. a liquid containing magnetic particles.

[0031] In the following description only those parts of an automatic clinical chemistry analyzer are described which are necessary to describe how a rack containing liquid containers or a movable part of such a rack is agitated by means of a shaker device.

15 EXAMPLE OF A RACK ACCORDING TO THE INVENTION

[0032] Fig. 1 shows a rack 11 according to the invention. Rack 11 has a frame 12 and a movable part 21. Frame 12 has at least one section 13 for holding a first liquid containing component which does not have to be agitated and at least one section 14 for holding a second liquid containing component which has to be agitated. The movable part 21 of the rack 11 is located in a section 14. The shape and size of section 14 allows movement of movable part 21 within predetermined limits.

[0033] Rack 11 is made e.g. of a polycarbonate (PC).

[0034] The first and the second liquid containing components are e.g. a single liquid container or a component comprising a casing 16 which contains one or more liquid containers 15. A component of the latter type is described in European Patent Application EP 0564970 A2.

[0035] Fig. 2 shows a rack 11 having a section 14 that holds a liquid containing a component of the type described in European Patent Application EP 0564970 A2. Such a component comprises e.g. a casing 16 wherein one or more containers 15 are lodged. Each of the containers 15 contains a liquid to be agitated.

40 EXAMPLE OF A FIRST EMBODIMENT OF ANALYZER ACCORDING TO THE INVENTION

[0036] Fig. 3 shows a perspective view of a part of an analyzer according to the invention which includes a rack of the type described above with reference to Figures 1 and 2.

[0037] A first embodiment of a shaker device which is part of this analyzer is described hereinafter with reference to Figures 4 to 8.

[0038] As shown by Fig. 3, the analyzer comprises several electromechanical shaker devices 31 each of which is adapted for being connected to a removable part 21 of rack 11.

[0039] Among the parts of shaker 31 represented in Fig. 3 are a carriage 34 and a disk 32 which carries an eccentric pin 36 and which is driven by a motor 33. Motor 33 is preferably a step motor.

[0040] Fig 4 shows a perspective view of shaker device

31. In Fig. 4 a carriage 34 which is part of shaker mechanism 31 is mechanically coupled to movable part 21 of rack 11. Carriage 34 is connected with a connection piece 38 by means of a joint 40. Connection piece 38 is rotatably connected to a cylindrical joint combined with a revolute joint 37 which is in turn connected with eccentric pin 36. The lower part of carriage 34 includes a slide bearing 53 which allows carriage 34 to slide back and forth along the length axis 39 of a guiding shaft 64 and also to oscillate back and forth around axis 39. Guiding shaft 64 has a fixed position and is parallel to the X-axis.

[0041] Fig. 4 also shows a support plate 68 for the frame 12 of rack 11.

[0042] As shown in Fig. 4, the eccentricity e is the distance that separates the axis of rotation 29 of motor 33 and the length axis of pin 36 from each other.

[0043] Fig. 5 shows a partial cross-sectional view of means for coupling movable part 21 of rack 11 with a carriage 34 of a shaker device 31 by means of a leaf spring 35. As shown by Figures 5 and 6, one end of leaf spring 35 is mechanically connected with movable part 21. Fig. 5 shows a rack 11 in a position at which movable part 21 is not engaged with carriage 34 by means of a leaf spring 35. In Fig. 5, a casing 16 containing liquid containers 15 which do not have to be agitated is mounted on section 13 of rack 11. When frame 12 of rack 11 is in the position represented in Fig. 5 with respect to carriage 34 of shaker device 31, movable part 21 is loosely connected with frame 12. This loose connection is achieved e.g. by means of pins 41, 42, 43 which cooperate with corresponding openings 51, 52 of removable part 21 shown in Fig. 2. Pins 41, 42, 43 are inserted in suitable openings of frame 12.

[0044] Fig. 6 shows a partial cross-sectional view of a movable part 21 of rack 11 coupled with carriage 34 of shaker device 31 by means of leaf spring 35. When frame 12 of rack 11 is in the position represented in Fig. 6 with respect to carriage 34 of shaker device 31, movable part 21 remains connected with frame 12.

[0045] As can be appreciated from Fig. 4, when disk 32 and thereby eccentric pin 36 are rotated by actuation of motor 33, pin 36 and joint 37 cause a movement of connection piece 38 and thereby of carriage 34, movable part 21 and liquid containers 15 in three orthogonal directions X, Y, Z within predetermined limits. Directions X, Y, Z are represented in Fig. 4. This motion is the result of the combination of two movements of connection piece 38: an oscillation of an angle ϕ around axis 39 and a back and forth motion in X direction.

[0046] The mechanical components of shaker device 31 are made e.g. of aluminum or of steel.

[0047] Fig. 7 shows curves representing the variation with time of the components of motion of carriage 34 in three orthogonal directions X, Y, Z and of an angular component ϕ corresponding to the oscillation of carriage 34 around axis 39.

[0048] Fig. 8 shows a three-dimensional path M of motion of a point of casing 16 when it is moved by shaker

device 31 shown by Fig. 4.

[0049] An encoder 28 (not shown in Fig. 4) is connected with motor 33 and is arranged in the housing of motor 33. The angular position of motor 33 is controlled by means of an encoder 28 which for this purpose receives signals from an electro-optical position detector 66 described hereinafter with reference to Figures 9 and 10. Control of the angular position of motor 33 by means of encoder 28 and detector 66 makes it possible to position liquid container carrier 16 and thereby liquid container 16 in a reproducible way, at a predetermined position, e.g. at the end of a shaking operation of shaker device 31.

EXAMPLE OF A SECOND EMBODIMENT OF AN ANALYZER ACCORDING TO THE INVENTION

[0050] The structure of this second analyzer embodiment is similar to the structure of the first embodiment described above, but this second analyzer embodiment comprises a second embodiment of a shaker device which is described hereinafter with reference to Figures 9 and 10.

[0051] Fig. 9 shows a perspective view of a shaker device 67 which is part of an analyzer according to the invention and which serves for moving the movable part 21 of rack 11 and thereby casing 16 in the same way as achieved with shaker 31 and thereby effect the motions represented in Figures 7 and 8.

[0052] Shaker device has a carriage 63 which has the same or similar structure and function as carriage 34 described above with reference to Figures 4-6.

[0053] Shaker device 67 is shown in detail in Fig. 10. Shaker device 67 differs from shaker device 31 represented in Fig. 4 in that it comprises a pin 61a inserted in a ball and socket joint 65 which as shown in Fig. 9 is directly connected to carriage 63 of shaker device 67 and not by means of a joint 37 and a connection piece 38 as is the case when shaker device 31 shown in Fig. 4 is used. Fig. 9 also shows support plate 68 for the frame 12 of rack 11. Pin 61a is driven by a shaft 61 of a step motor 33.

[0054] Fig. 10 also shows the eccentricity e of pin 61a, i.e. the distance e between the length symmetry axis 61b of pin 61a and the rotation axis 29 of shaft 61 of motor 33.

[0055] The lower part of carriage 63 includes a slide bearing 62 which allows carriage 63 to slide back and forth along the length axis 39 of a guiding shaft 64 and also to oscillate back and forth around axis 39. Guiding shaft 64 has a fixed position and is parallel to the X-axis.

[0056] When motor 33 is actuated, a motion transmitted to carriage 63 by pin 61a and joint 65 moves carriage 63 back and forth along the length axis 39 of guiding shaft 64 and also oscillates carriage 63 back and forth around axis 39.

[0057] Figures 9 and 10 also show an electro-optical position detector 66 which accurately detects the angular position of motor shaft 61. Detector 66 provides signals

to an encoder (not shown in the figures) which serves for accurately positioning motor shaft 61. Control of the angular position of motor shaft 61 by means of the encoder and detector 66 makes it possible to position liquid container carrier 16 and thereby liquid container 16 in a reproducible way, at a predetermined position, e.g. at the end of a shaking operation of shaker device 67.

EXAMPLE OF A THIRD EMBODIMENT OF AN ANALYZER ACCORDING TO THE INVENTION

[0058] Fig. 11 shows a part of a third embodiment of an analyzer according to the invention. This embodiment differs from the above described first and second embodiments in that it does not use the type of rack described above with reference to Figures 1 and 2, but a rack 11a built as a single piece frame 12 having a shape adapted for receiving liquid containers 16.

[0059] As shown by Fig. 11 the third embodiment of the analyzer also comprises a shaker device 70 which has a similar structure as shaker device 67 in Fig. 9. Shaker device 70 comprises a movable support plate 79 adapted for receiving rack 11a. Rack 11a and movable plate 79 are adapted for being removably connectable with each other.

[0060] The lower part of movable plate 79 is formed as a guiding support member 77.

[0061] As shown by Fig. 12 shaker device 70 further comprises an eccentric pin 71a driven by a shaft 71 of a step motor 33.

[0062] Pin 71a is inserted in a ball and socket joint 78 which, as shown in Fig. 12, is directly connected to support member 77 of movable plate 79.

[0063] Fig. 12 also shows the eccentricity e of pin 71a, i.e. the distance e between the length symmetry axis 71b of pin 71a and the rotation axis 29 of shaft 71 of motor 33.

[0064] The lower part of guiding support member 77 includes a slide bearing 72 which allows support member 77 and thereby movable plate 79 to slide back and forth along the length axis 39 of a guiding shaft 75 and also to oscillate back and forth around axis 39. Guiding shaft 75 has a fixed position and is parallel to the X-axis.

[0065] When motor 33 is actuated, a motion transmitted to movable plate 79 by pin 71a and joint 78 moves movable plate 79 back and forth along the length axis 39 of guiding shaft 75 and also oscillates movable plate 79 back and forth around axis 39.

[0066] Shaker device 70 moves rack 11a and thereby casing 16 in the same way as achieved with shaker 31 in the embodiment described with reference to Figures 1-8. Casing 16 in Fig. 11 is thus moved by shaker device 70 as represented in Figures 7 and 8.

[0067] Figures 11 and 12 also show an electro-optical position detector 66 which accurately detects the angular position of motor shaft 71. Detector 66 provides signals to an encoder (not shown in the figures) which serves for accurately positioning motor shaft 71. Control of the angular position of motor shaft 71 by means of the encoder

and detector 66 makes it possible to position liquid container carrier 16 and thereby liquid container 16 in a reproducible way, at a predetermined position, e.g. at the end of a shaking operation of shaker device 70.

EXAMPLE OF A FOURTH EMBODIMENT OF AN ANALYZER ACCORDING TO THE INVENTION

[0068] Fig. 13 shows a part of a fourth embodiment of an analyzer according to the invention. This fourth embodiment also uses a rack 11a of the type shown in Fig. 11 and comprises a movable support plate 89 similar to movable plate 79 of the third embodiment.

[0069] This fourth embodiment of an analyzer according to the invention differs from the above described third analyzer embodiment in that it comprises a shaker device 80 which is not connected to the lower and central part of the movable plate, but to one end thereof formed as a bar 87.

[0070] As shown by Fig. 13 shaker device 80 has a similar structure as shaker device 70 in Fig. 11.

[0071] Shaker device 80 comprises a movable support plate 89 adapted for receiving rack 11a. Rack 11a and movable plate 89 are adapted for being removably connectable with each other.

[0072] As shown by Fig. 14 shaker device 80 further comprises an eccentric pin 81a driven by a shaft 81 of a step motor 33.

[0073] Pin 81a is inserted in a ball and socket joint 88 which as shown in Fig. 14 is directly connected to bar 87 at one end of movable plate 89.

[0074] Fig. 14 also shows the eccentricity e of pin 81a, i.e. the distance e between the length symmetry axis 81b of pin 81a and the rotation axis 29 of shaft 81 of motor 33.

[0075] The lower part of movable plate 89 is formed as a guiding support member which includes slide bearings 82 which allow movable plate 89 to slide back and forth along the length axis 39 of guiding shafts 84 and 85 and also to oscillate back and forth around axis 39. Guiding shafts 84 and 85 have a fixed position and are parallel to the X-axis.

[0076] When motor 33 is actuated, motion transmitted to movable plate 89 by pin 81a and joint 88 moves movable plate 89 back and forth along the length axis 39 of guiding shafts 84 and 85 and also oscillates movable plate 89 back and forth around axis 39.

[0077] Shaker device 80 also moves rack 11a and thereby casing 16 in the same way as achieved with shaker 31 in the embodiment described with reference to Figures 1-8. Casing 16 in Fig. 11 is thus moved by shaker device 80 as represented in Figures 7 and 8.

[0078] Figures 13 and 14 also show an electro-optical position detector 66 which accurately detects the angular position of motor shaft 81. Detector 66 provides signals to an encoder (not shown in the figures) which serves for accurately positioning motor shaft 81. Control of the angular position of motor shaft 81 by means of the encoder and detector 66 makes it possible to position liquid con-

tainer carrier 16 and thereby liquid container 16 in a reproducible way, at a predetermined position, e.g. at the end of a shaking operation of shaker device 80.

Claims

1. A rack (11) for holding containers containing liquids used in clinical chemistry analyzers, said rack comprising

(a) a frame (12) having two or more sections, each section (13, 14) being adapted for receiving a liquid containing component, at least one of the sections (13) of said frame (12) being adapted for receiving a first liquid containing component which is adapted for being removably but tightly mechanically connected to said frame,

(b) at least one movable part (21) adapted to be removably coupled to a shaker device, said movable part being adapted for receiving and holding a second liquid containing component, at least one of the sections (14) of said frame being adapted for receiving said movable part (21) and allowing motion of said movable part (21) within predetermined limits.

2. A rack according to claim 1, wherein said at least one movable part (21) is adapted for being positioned within a section (14) of that frame (12) and for being loosely connected with said frame when said movable part (21) is not coupled to said shaker device.

3. A rack according to claim 2, wherein said movable part (21) remains connected with said frame (12) when said movable part (21) is coupled to said shaker device.

4. A rack according to claim 1, wherein said at least one movable part (21) and said second liquid containing component are movable within predetermined limits in three directions (X, Y, Z) which are orthogonal to each other.

5. A rack according to claim 1, wherein said at least one movable part (21) and said second liquid containing component are adapted to be subject to a combined motion comprising an axial displacement along a first axis within predetermined limits and a oscillation around a second axis within predetermined angular limits, said first axis and said second axis being parallel to each other.

6. An automatic analyzer for analyzing biological samples by means of a clinical chemistry method, said analyzer comprising

(a) a rack (11) for holding containers containing liquids used in clinical chemistry analyzers, said rack comprising

(a.1) a frame (12) having two or more sections (13, 14), each section being adapted for receiving a liquid containing component, at least one of the sections (13) of said frame being adapted for receiving a first liquid containing component which is adapted for being removably but tightly mechanically connected to said frame,

(a.2) at least one movable part (21) adapted to be removably coupled to a shaker device (31), said movable part (21) being adapted for receiving and holding a second liquid containing component, and

(b) an electromechanical shaker device (31) for shaking said at least one movable part (21) of said rack, said shaker device (31) and said movable part (21) being adapted to be removably connected with each other.

7. An automatic analyzer according to claim 6, wherein said shaker device (31) comprises

(a) an eccentric pin (36) driven by a motor (33), and

(b) mechanical means (37, 38, 34) which are connected to said pin (36) and which are connectable to said at least one movable part (21) for moving said movable part (21) when said eccentric pin (36) is rotated by said motor.

8. An automatic analyzer according to claim 7, wherein said movable part (21) is subject to a combined motion in three directions (X, Y, Z) which are orthogonal to each other when said pin (36) is rotated by said motor.

9. An automatic analyzer according to claim 7, wherein said movable part (21) is subject to a combined motion comprising an axial displacement along an axis (39) within predetermined limits and a oscillation about said axis (39) within predetermined angular limits when said eccentric pin (36) is rotated by said motor (33).

10. An automatic analyzer for analyzing biological samples by means of a clinical chemistry method, said analyzer comprising

(a) a rack (11a) for holding containers (16) containing liquids used in clinical chemistry analyzers, and

(b) an electromechanical shaker device (70, 80) for shaking said rack, said shaker device (70,

80) having a movable plate (79, 89) adapted for receiving said rack (11a), said rack (11a) and said movable plate (79, 89) being removably connectable with each other,

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said shaker device (70, 80) further comprising

(a) an eccentric pin (71a, 81a) driven by a motor (33), and

(b) mechanical means which connect said eccentric pin (71a, 81a) with said movable plate (79, 89).

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11. An automatic analyzer according to claim 12, wherein said shaker device (70) comprises a joint (78) which is adapted to receive said eccentric pin (71a), said joint (78) being connected to the bottom part of a guiding support member (77) which is part of or connected with said movable plate (79).

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12. An automatic analyzer according to claim 12, wherein said shaker device (80) comprises a joint (88) which is adapted to receive said eccentric pin (81a), said joint (88) being connected to a bar (87) which is an end part of said movable plate (89), said end part being located at one end of said plate along the length axis thereof.

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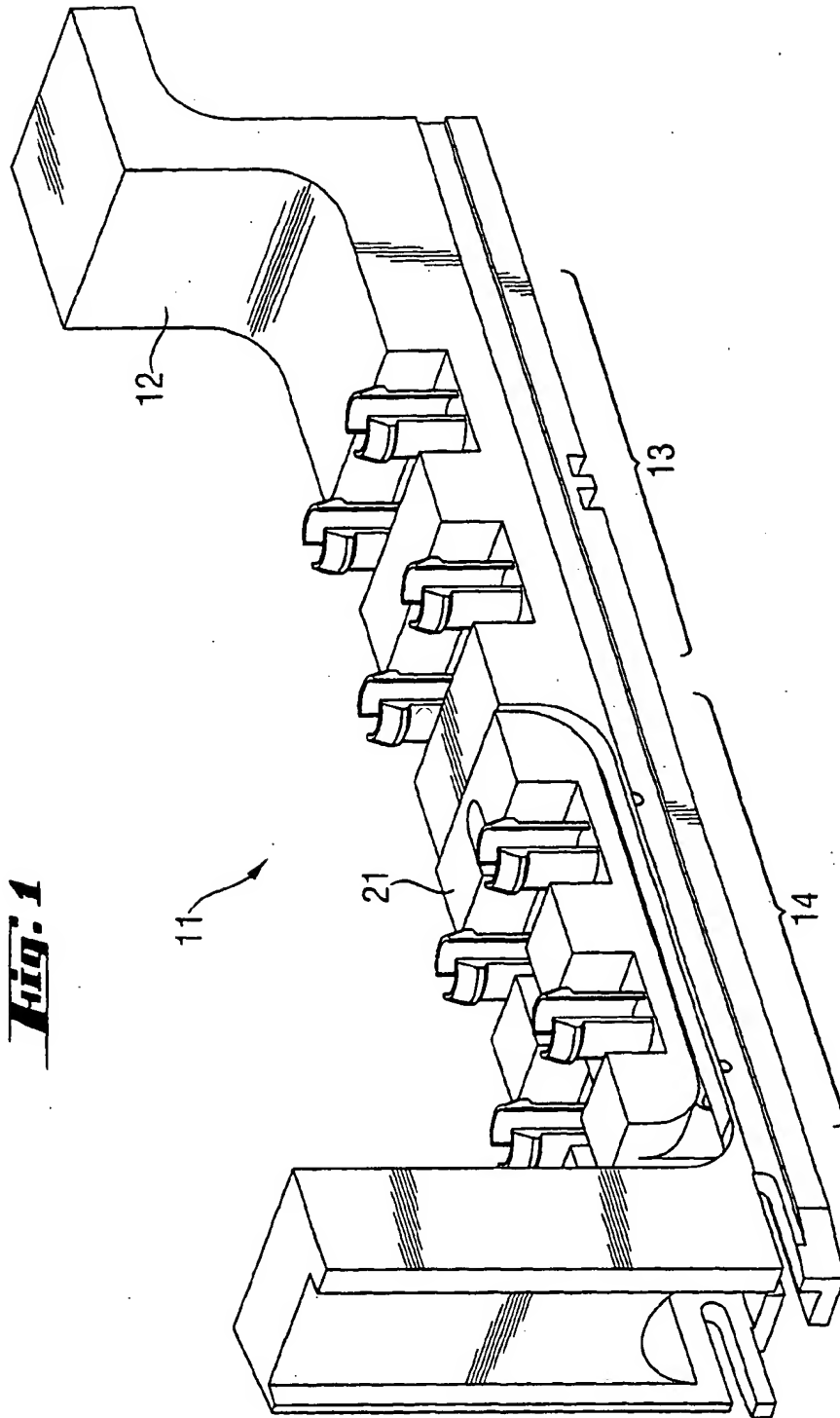


Fig. 1

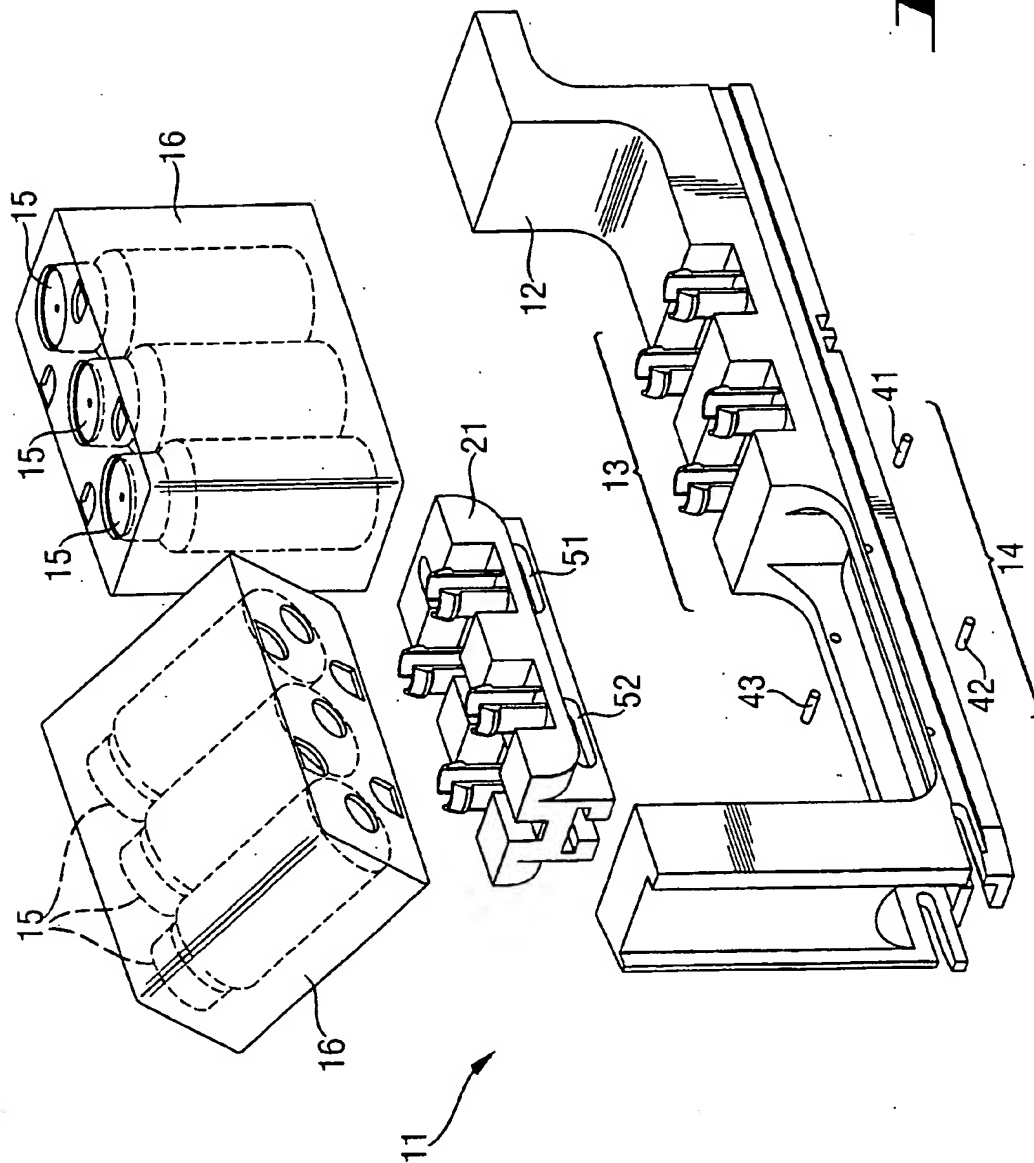


Fig. 2

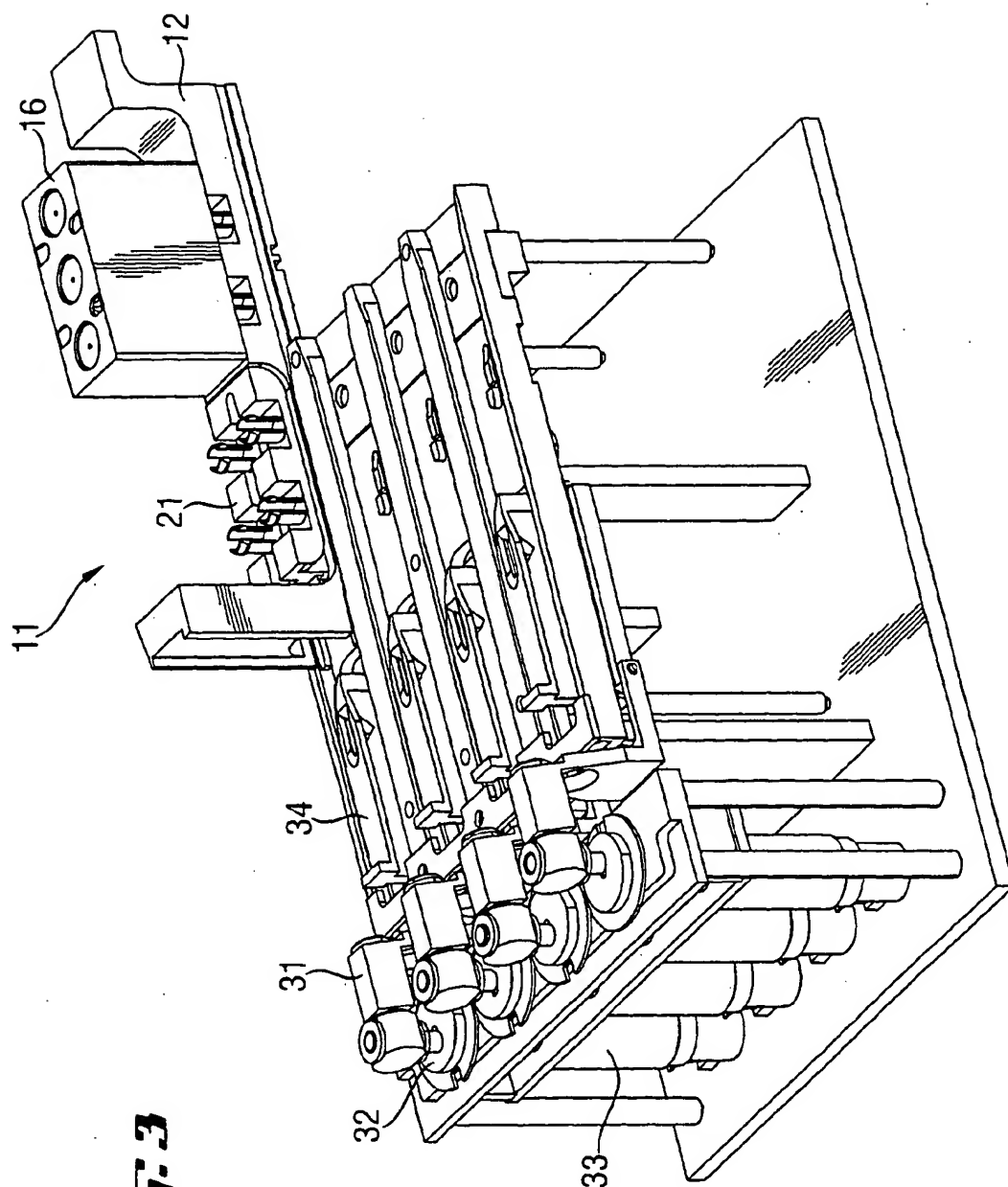
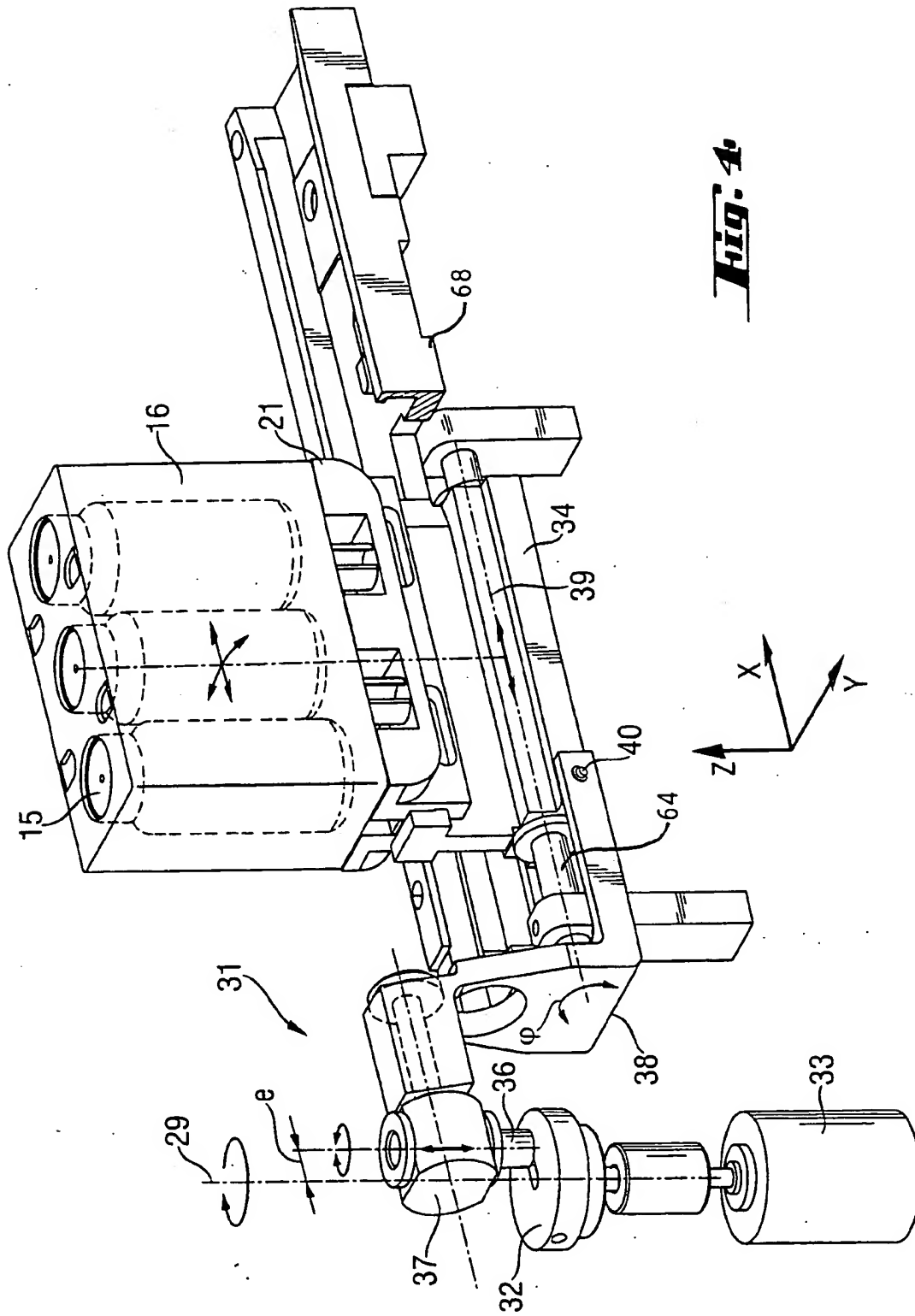
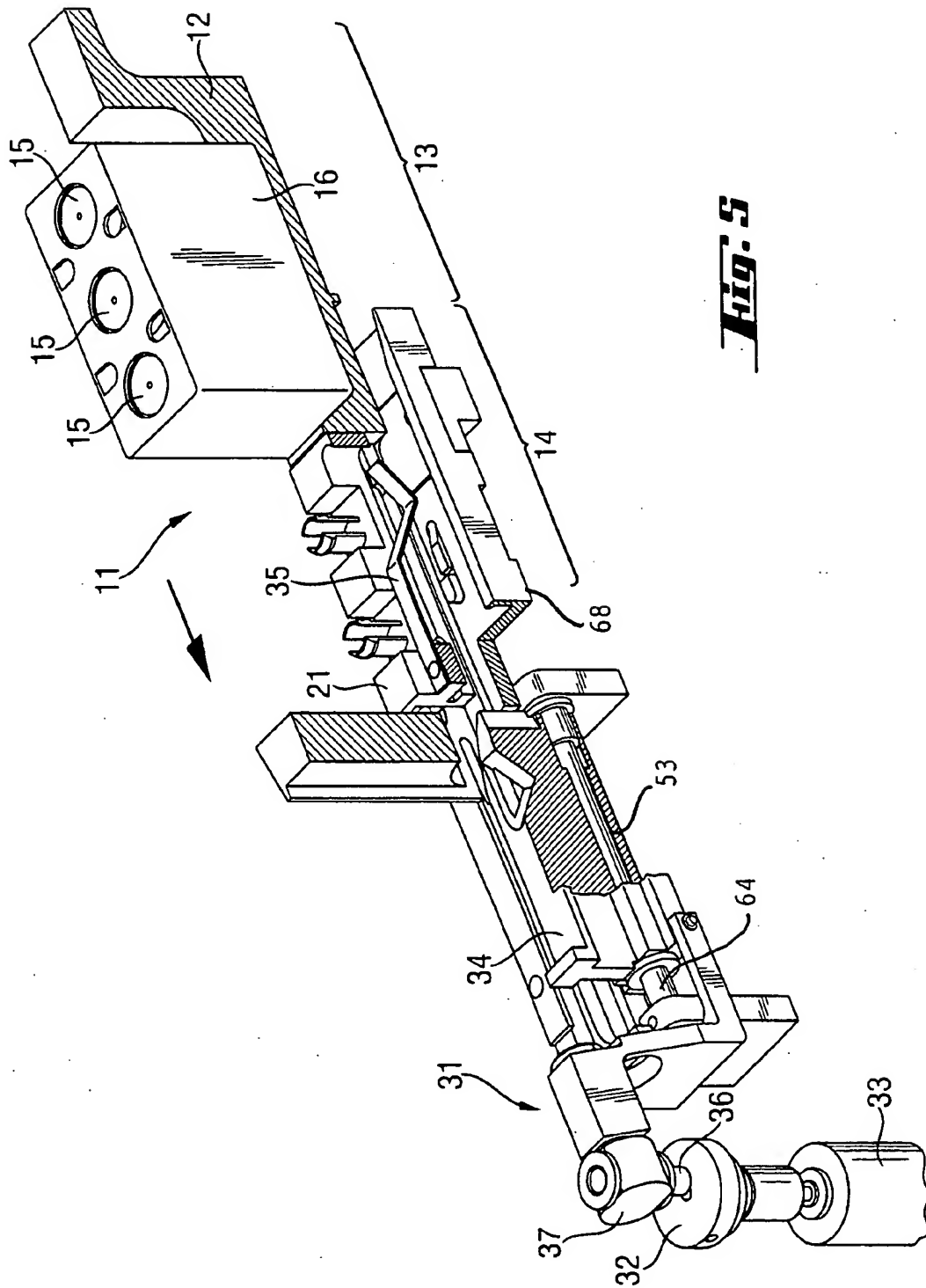


Fig. 3





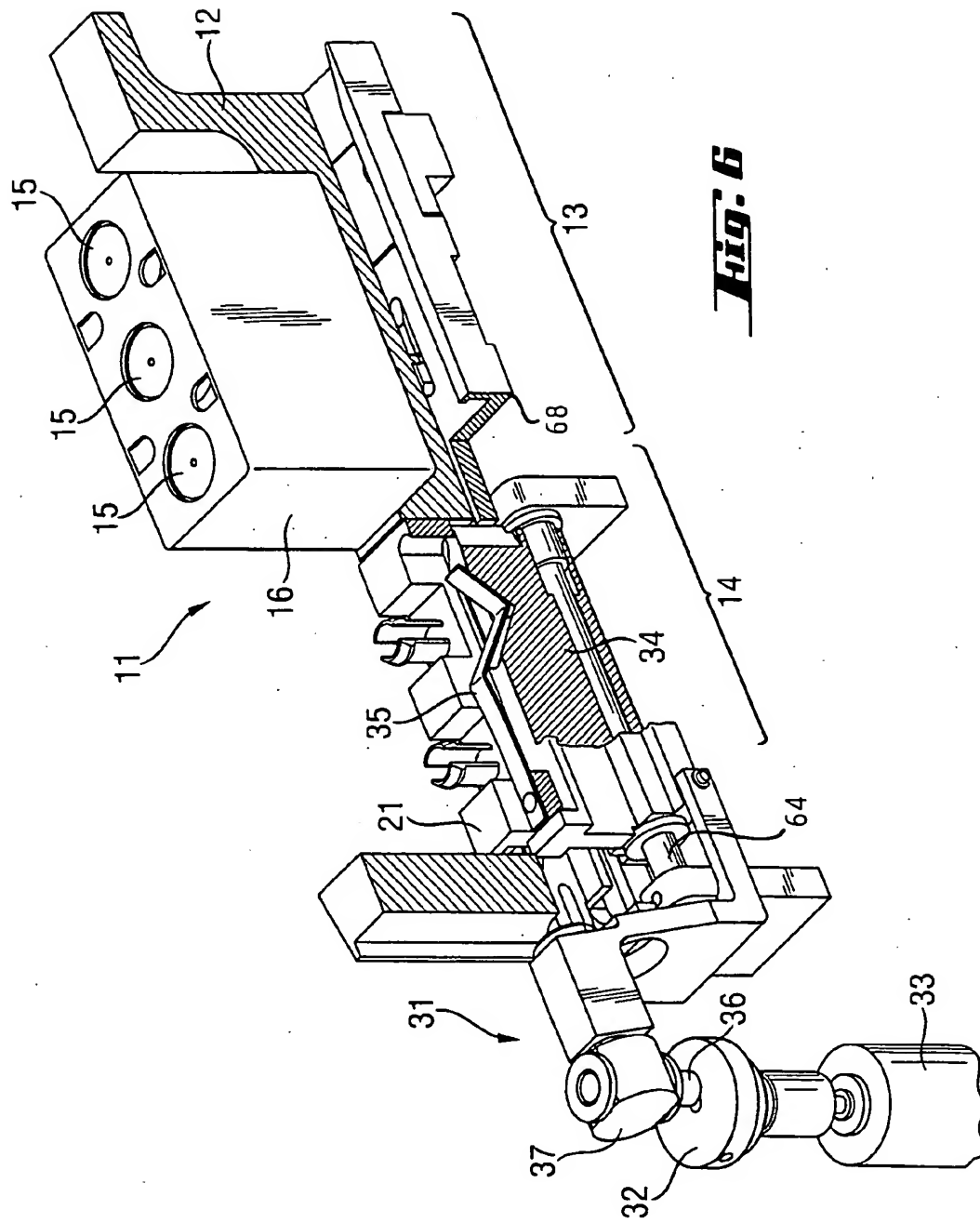


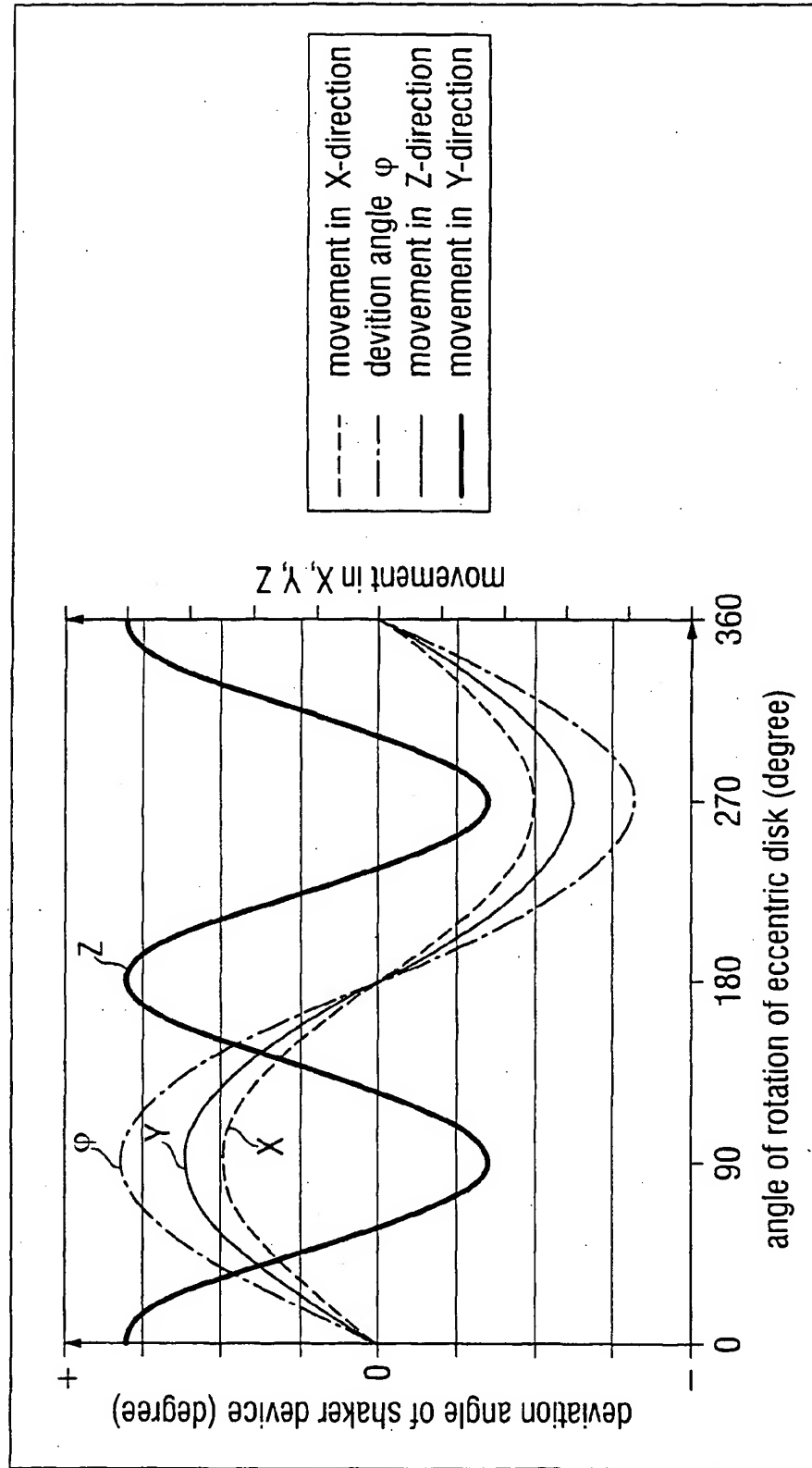
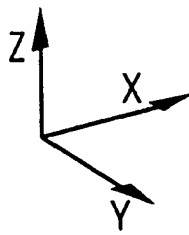
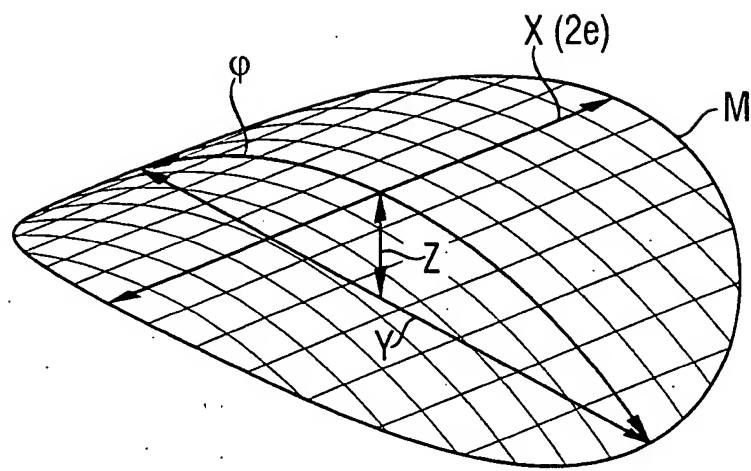
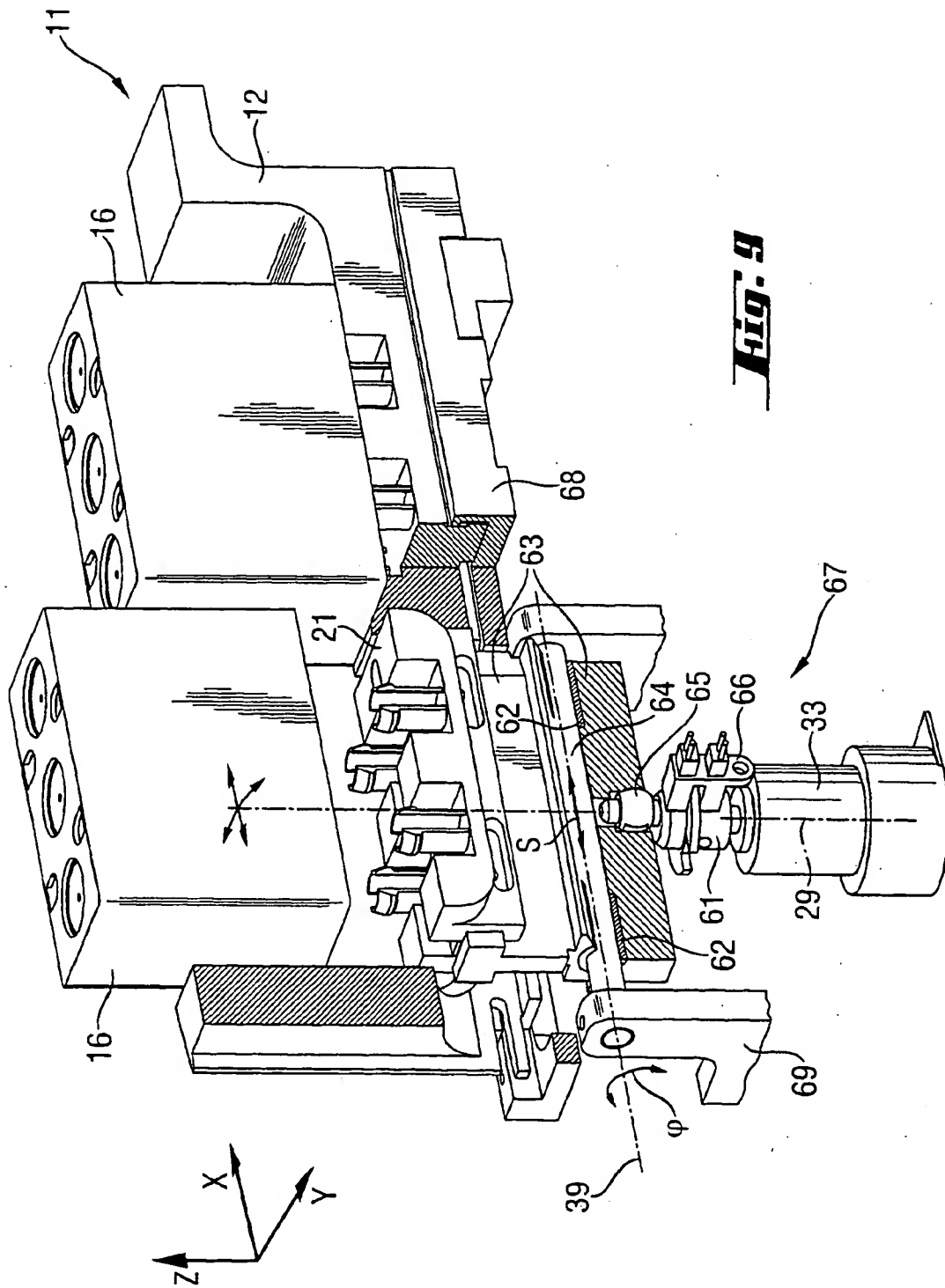
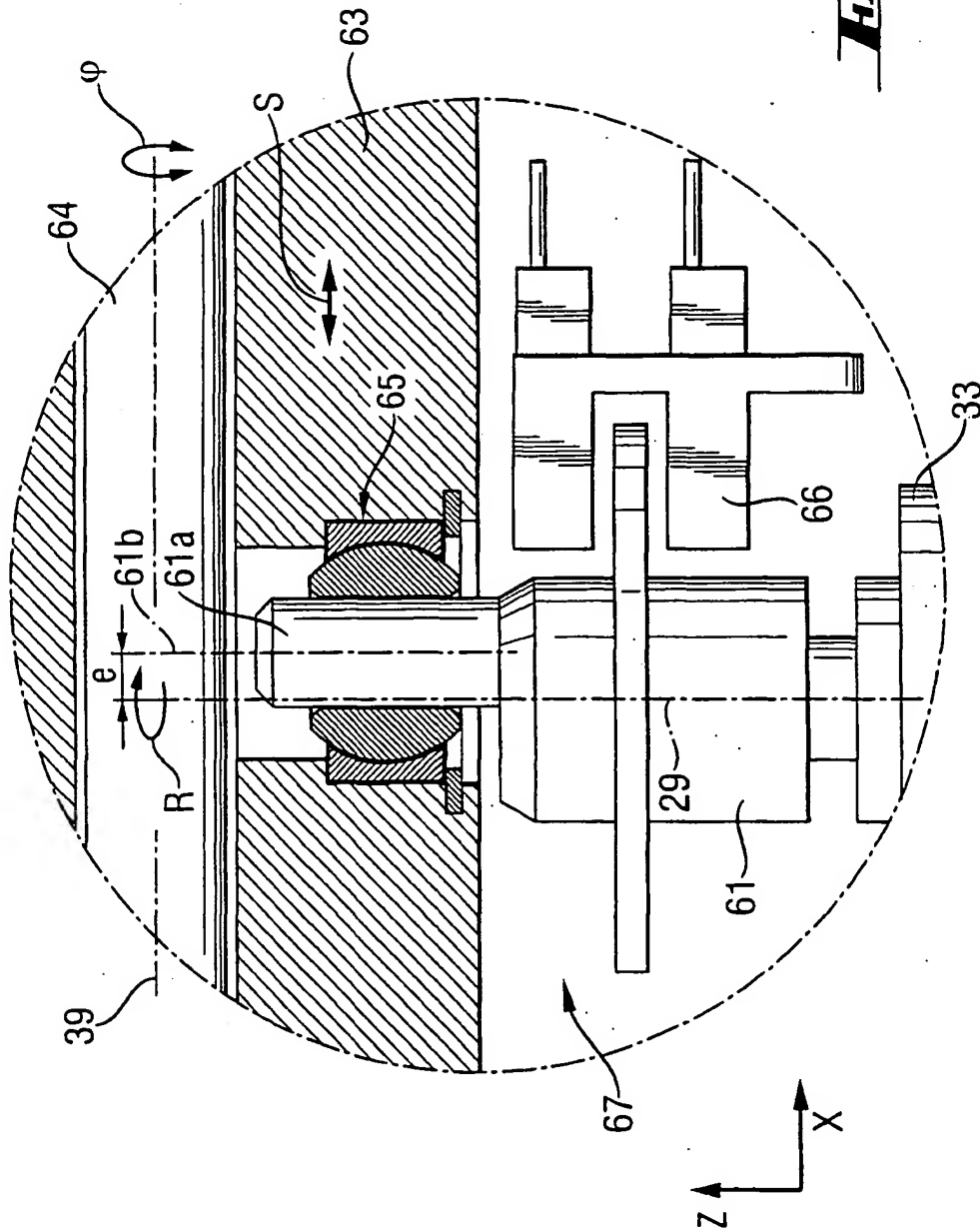
Fig. 2

Fig. 8





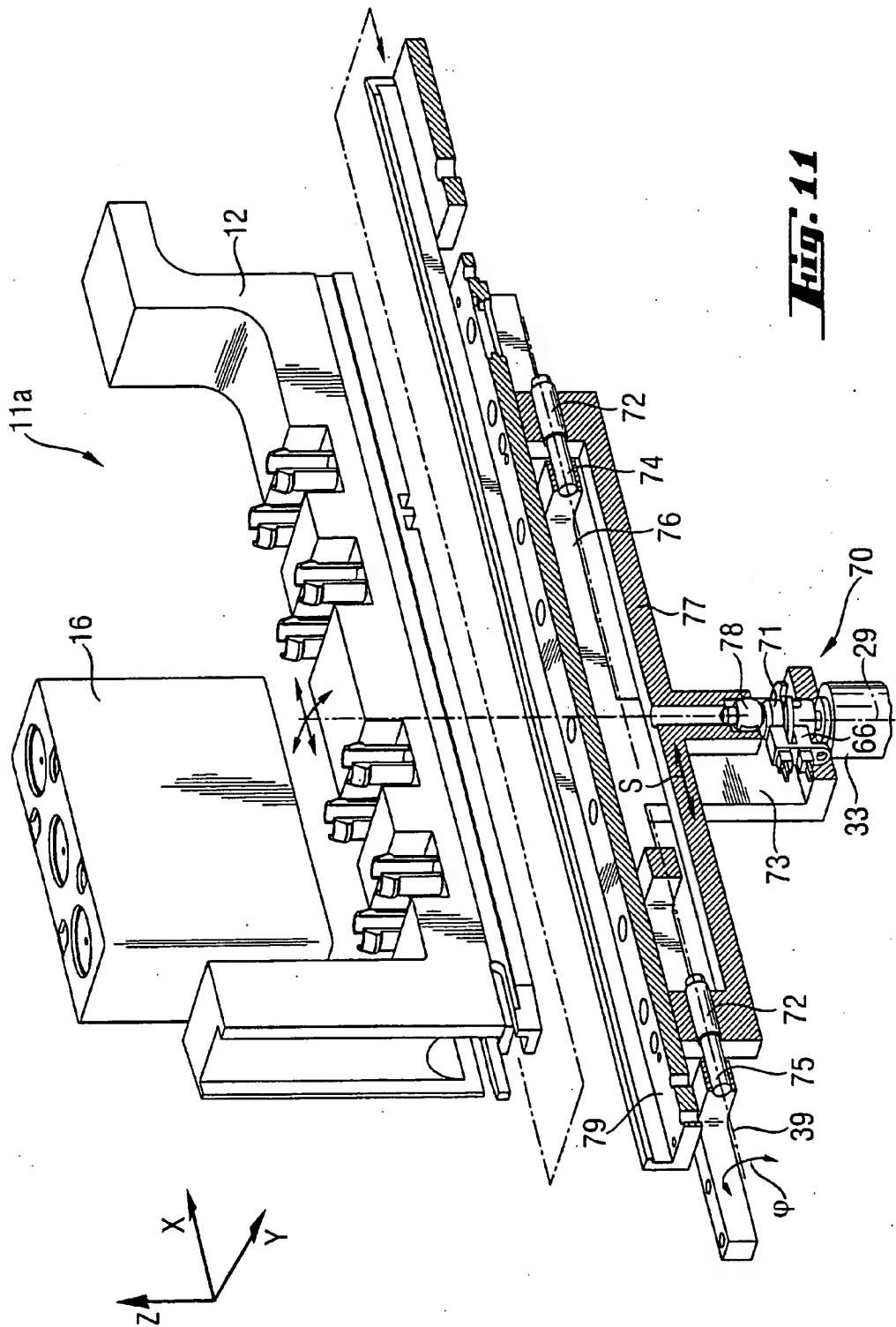
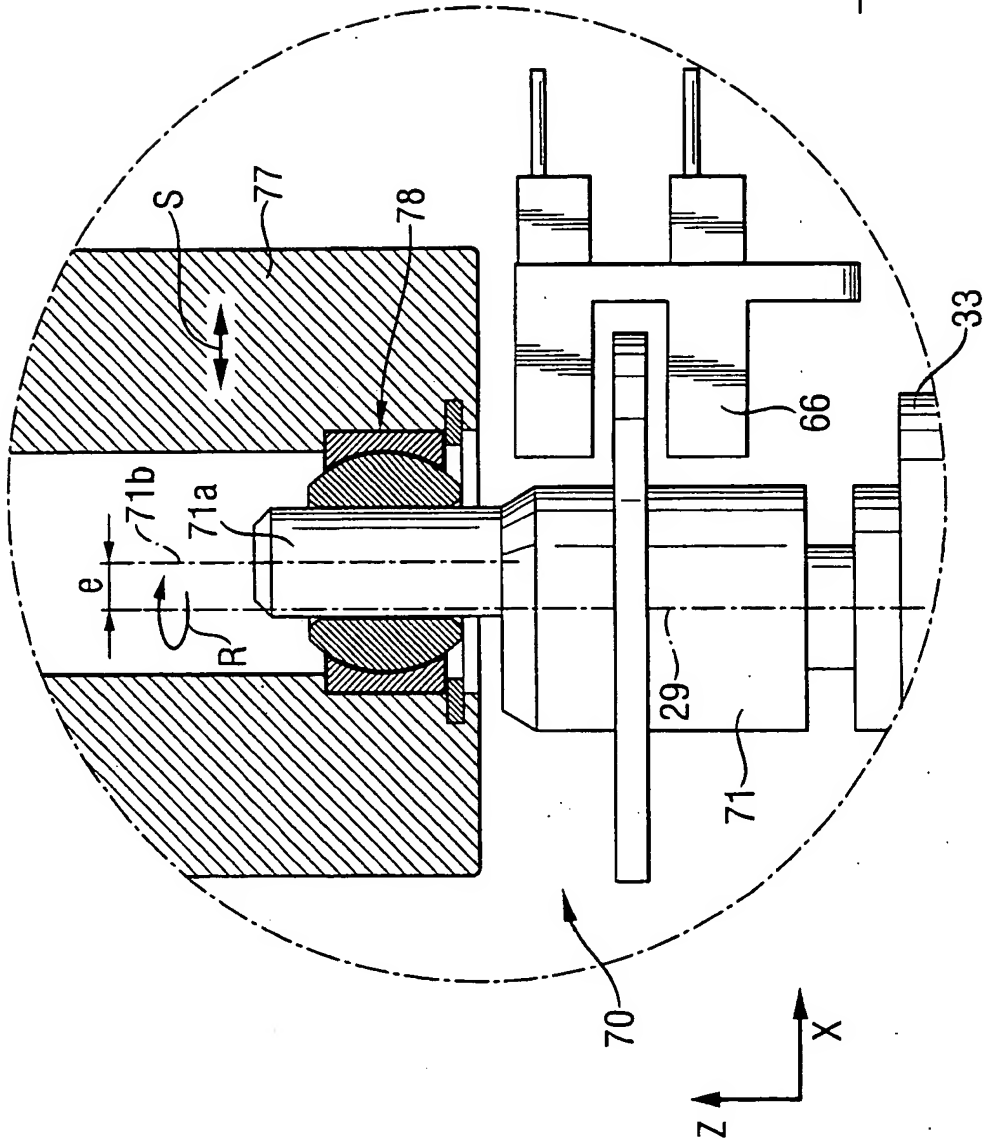
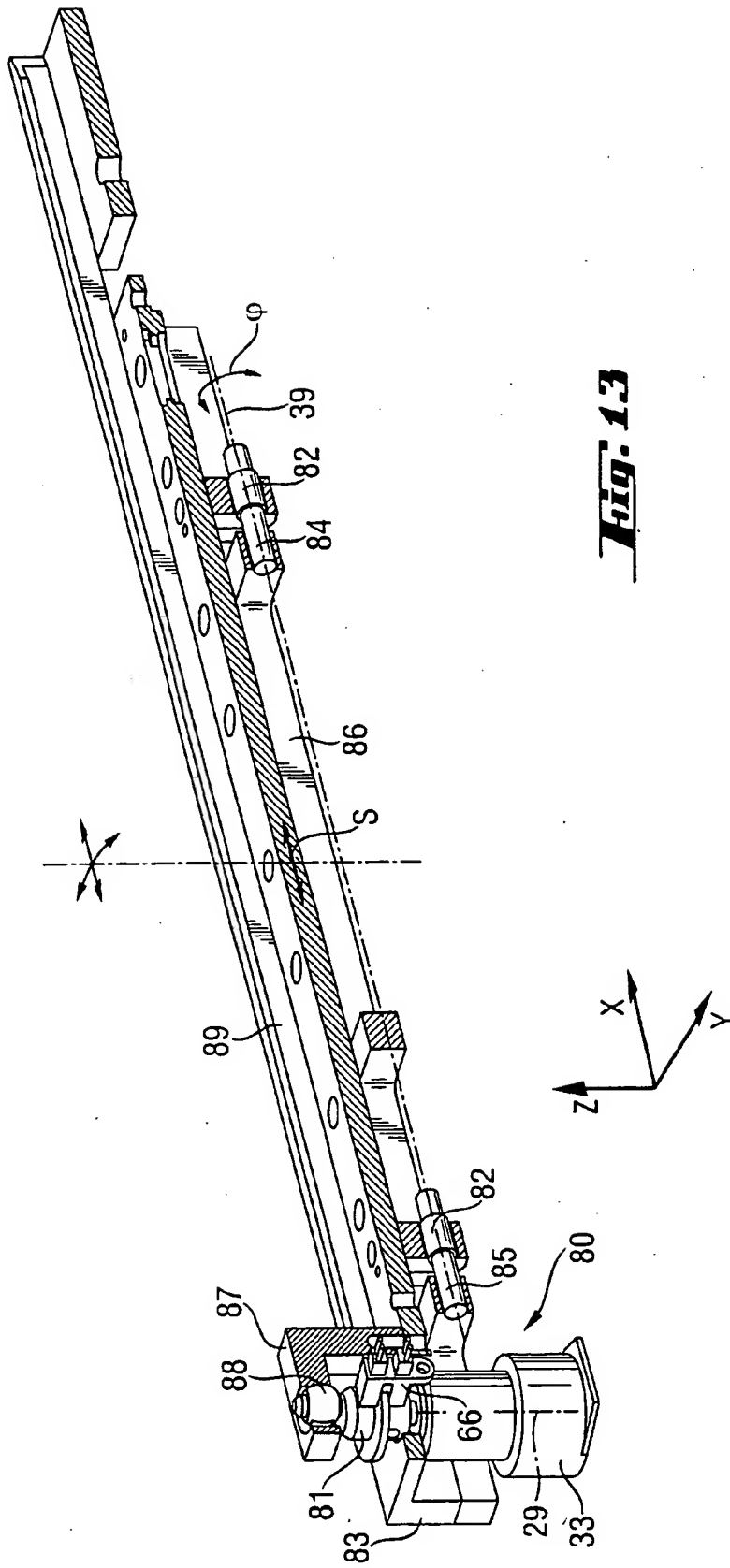
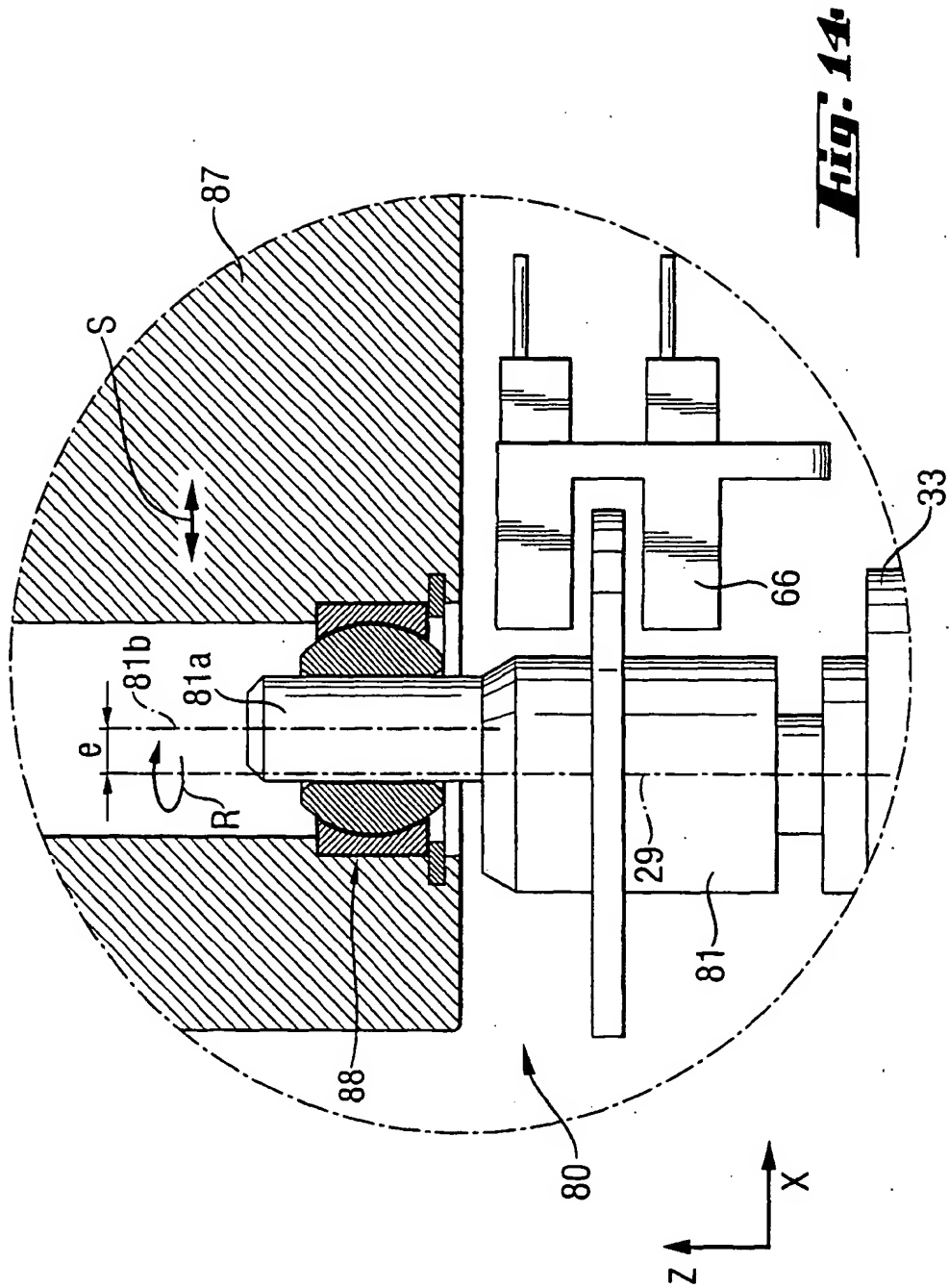


Fig. 12









European Patent
Office

EUROPEAN SEARCH REPORT

Application Number

EP 04 07 8041

DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int.Cl.7)
X	WO 98/57739 A (CHEMSPEED LTD; GUELLER, ROLF; MUNCH, SERAPHIN; GEES, THOMAS; TSCHIRKY,) 23 December 1998 (1998-12-23) * page 16, line 24 - page 18, line 25 * * page 28, line 27 - page 29, line 5 * * figures 1-6,29 *	1-12	B01L9/06 G01N35/04
A	WO 01/28680 A (GENTRA SYSTEMS, INC) 26 April 2001 (2001-04-26) * page 5 - page 6 * * figures 1,2 *	1-12	
A	US 5 632 388 A (MORRISON ET AL) 27 May 1997 (1997-05-27) * figures 1-3 *	1-12	
A	US 5 665 309 A (CHAMPSEIX ET AL) 9 September 1997 (1997-09-09) * the whole document *	1-12	
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The present search report has been drawn up for all claims			
Place of search Munich		Date of completion of the search 26 April 2005	Examiner Timonen, T
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